

Zonal Flows and their stability: The role they play in L-H Transitions and density limits

P. N. GUZDAR INSTITUTE FOR RESEARCH IN ELECTRONICS AND APPLIED PHYSICS (IREAP) UNIVERSITY OF MARYLAND

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IN COLLABORATION WITH R.G. KLEVA , UMD, USA A. DAS AND P. K. KAW, IPR GANDHINAGAR, INDIA N. CHAKRABARTI, SINP, KOLKATA, INDIA R.J. GROENBER AND P. GOHIL, GA, SAN DIEGO



OUTLINE OF THE TALK

- GENERAL INTRODUCTION
- •SIMULATION RESULTS
- •THEORETICAL MODEL
- •COMPARISON WITH EXPERIMENTS
- CONCLUSIONS

Physics issues

- •What physics is responsible for L-H Transitions ?
- Which mode/modes is/are responsible for transport in the edge ?
- How does zonal flow get generated and what is its role in transition?

More pragmatic issues

- Why is the power threshold (in most machines) when ∇B drift is away from the X-point 2 -4 larger compared to the case when ∇B drift is towards the X-point ?
- Why does the pellet injection reduce the threshold power for the transition ?
- Can the same physics be playing a role in triggering an H-mode in tokamaks with an imposed electric field ?



3D SIMULATION GEOMETRY

3D NONLINEAR SIMULATIONS OF RBM





BASIC EQUATIONS

A. Zeiler, J, F. Drake and B. Rogers, Phys. Plasmas 4, 2134, 1997

$$\begin{split} \frac{dn}{dt} &+ \frac{c_s^2}{\Omega_i L_n} \frac{\partial \phi}{\partial y} + \frac{2c_s^2}{\Omega_i} \vec{b} \times \vec{\kappa} \cdot \nabla(\phi - n) - \nabla_{\parallel} J + c_s \nabla_{\parallel} v_{\parallel} = 0 \\ & \frac{c_s^2}{\Omega_i^2} \nabla_{\perp} \cdot \frac{d}{dt} \nabla_{\perp} \phi - \frac{2c_s^2}{\Omega_i} \vec{b} \times \vec{\kappa} \cdot \nabla p_e - \nabla_{\parallel} J = 0 \\ & \frac{1}{v_A} \frac{\partial \psi}{\partial t} + \frac{c_s^2}{v_A \Omega_i L_p} \frac{\partial \psi}{\partial y} - \nabla_{\parallel} (\phi - n) = \frac{J}{\sigma} \\ & \frac{dv_{\parallel}}{dt} = -c_s \bigg[\nabla_{\parallel} p_e + \frac{c_s^2}{v_A \Omega_i L_p} \frac{\partial \psi}{\partial y} \bigg] \end{split}$$



BASIC EQUATIONS-CONTINUED

$$\frac{c_{s}^{2}}{\Omega_{i}^{2}}\nabla_{\perp}\cdot\frac{d}{dt}\nabla_{\perp}\phi-\frac{2c_{s}^{2}}{\Omega_{i}}b\times\kappa\cdot\nabla p_{e}-\nabla_{\parallel}J=0$$

$$\mathbf{x}_{\perp} \rightarrow \mathbf{x}_{\perp}/\mathbf{L}_{0}, \ \mathbf{x}_{\parallel} \rightarrow \mathbf{x}_{\parallel}/\mathbf{L}_{\parallel}, \ \mathbf{t} \rightarrow \mathbf{t}/\mathbf{t}_{0} \qquad \mathbf{L}_{\parallel} = 2\pi q \mathbf{R}, \ \mathbf{n}/\mathbf{t}_{0} \sim \mathbf{c}_{s}^{2} \phi / \mathbf{L}_{0} \mathbf{L}_{n} \mathbf{\Omega}_{i}, \ \mathbf{J} \sim \sigma \nabla_{\parallel} \phi$$

$$1 \qquad : \quad \frac{\mathrm{RL}_{n}}{2\mathrm{c}_{s}^{2}} t_{0}^{2} \quad : \quad \frac{4\pi \mathrm{v}_{A}^{2} \eta_{\parallel} t_{0} \mathrm{L}_{0}^{2}}{\mathrm{c}^{2} \mathrm{L}_{\parallel}^{2}}$$

$$\Rightarrow t_0 = c_s \left(\frac{2}{RL_n}\right)^{1/2} \qquad L_0 = \frac{L_{\parallel}c}{v_A} \left(\frac{\eta_{\parallel}}{4\pi t_0}\right)^{1/2}$$

Two dimensionless parameters: (1) $\alpha_{\rm D} = \omega_* t_0$ (2) $\alpha_{\rm MHD} = \left(\frac{v_{\rm A}}{qR}t_0\right)^2$



Rogers, Drake and Zeiler, PRL, 81, 4396, 1998





Rogers, Drake and Zeiler, PRL, 81, 4396, 1998 Simulations with evolving density profile





FIG. 4. (a) Γ_{p_i} vs t; (b) \bar{v}_{iy} (solid line); \bar{v}_{diy} (dashed line); \bar{v}_{Ey} (dotted line).

FIG. 5. (a) $\mathbf{E} \times \mathbf{B}$ flows before (dashed line), during (solid line), after (dotted line) transition; (b) early (dashed line), late (solid line) p_i profiles.





- · L-mode turbulence in the drift wave-like regime (not the resistive ballooning regime)
- Increase in plasma β caused larger anomalous transport even for $\alpha_{MHD} < 1.0$ Rogers and Drake, Phys. Rev. Lett. **79**, 229 (1997)



- Multiple zonal "layers" which evolve into single layer after transition
- zonal/shear flow present in the L-mode phase zonal/shear flow necessary but not sufficient for L-H transitions

IF ZONAL FLOW IS RESPONSIBLE FOR TRANSITION IT IS NECESSARY TO STUDY THE GENERATION MECHANISM IN FINITE BETA PLASMAS



"MODULATION" INSTABILITY







LINEAR INSTABILITY ANALYSIS

Guzdar et al., PRL, 86, 15001, 2001, Guzdar et al., PoP





two side bands

with
$$\omega_{\pm} = \omega \pm \omega_0$$



$$\nabla_{\parallel} \rightarrow ik_{\parallel} = i(m - nq) / Rq$$

$$(\omega + \Delta)\phi_{+} = i\Gamma_{z}\left[\phi_{0}\phi_{s}M_{A}(k_{x}, k_{y}) + \frac{\omega_{0}}{k_{\parallel}v_{A}}\phi_{0}\psi_{s}M_{B}(k_{x}, k_{y})\right]$$

$$(\omega - \Delta)\phi_{-} = -i\Gamma_{z}\left[\phi_{0}^{*}\phi_{s}M_{A}(k_{x}, k_{y}) + \frac{\omega_{0}}{k_{\parallel}v_{A}}\phi_{0}^{*}\psi_{s}M_{B}(k_{x}, k_{y})\right]$$

$$\left(\omega + i\nu_{\phi}\right)\phi_{s} = i\Gamma_{z}\left[1 - \left(\frac{\omega_{0}}{k_{\parallel}v_{A}}\right)^{2}\right]\left[\phi_{0}^{*}\phi_{+} - \phi_{0}\phi_{-}\right]$$

$$\left(\omega + i\nu_{\psi}\right)\psi_{s} = i\Gamma_{z}(k_{x}^{2}\rho_{s}^{2})\frac{\omega_{0}}{k_{\parallel}v_{A}}\left[\phi_{0}^{*}\phi_{+} - \phi_{0}\phi_{-}\right]$$



"LOCAL" INSTABILITY ANALYSIS (2)

$$\begin{split} \mathbf{M}_{A} &= \frac{(1+\tau)(1+k_{y}^{2}\rho_{s}^{2}\tau)}{\left(1+\frac{\omega_{*e}}{\omega_{0}}\tau\right)A} - \frac{\omega_{0}^{2}}{k_{\parallel}^{2}v_{A}^{2}A} \left[\frac{1+k_{\perp}^{2}\rho_{s}^{2}\tau}{1+k_{y}^{2}\rho_{s}^{2}\tau} \left(1+\frac{\omega_{*e}}{\omega_{0}}\tau\right) + (1+\tau)\left(1-\frac{\omega_{*e}}{\omega_{0}}\right)\right] + \\ &\left[\frac{\omega_{0}^{2}}{k_{\parallel}^{2}v_{A}^{2}} \left(1-\frac{\omega_{*e}}{\omega_{0}}\right) - k_{\perp}^{2}\rho_{s}^{2}\right] \left[\frac{k_{x}^{2}-k_{y}^{2}}{k_{\perp}^{2}} - \tau\frac{k_{y}^{2}}{k_{\perp}^{2}} \left(\frac{\omega_{*e}}{\omega_{0}} - k_{y}^{2}\rho_{s}^{2}\right)}{1+k_{y}^{2}\rho_{s}^{2}\tau}\right] \right] /A \end{split}$$

$$M_{B} = \left[-\frac{2k_{y}^{2}}{k_{\perp}^{2}} \frac{1+k_{\perp}^{2}\rho_{s}^{2}\tau}{1+k_{y}^{2}\rho_{s}^{2}\tau} \left(1-\frac{\omega_{*e}}{\omega_{0}} + k_{y}^{2}\rho_{s}^{2} \right) \right] / A$$

$$\Gamma_{z} = \frac{k_{x}k_{y}c_{s}^{2}}{\Omega_{i}} \qquad \Delta = k_{x}^{2}\rho_{s}^{2}\omega_{0}(1+\tau)/A$$



"LOCAL" INSTABILITY ANALYSIS (3)

$$A = 1 + k_{\perp}^{2} \rho_{s}^{2} (1 + \tau) - 3 \frac{\left\{ \omega_{0} \left[\omega_{0} + \frac{2}{3} \omega_{*e} (\tau - 1) \right] - \frac{1}{3} \omega_{*e}^{2} \tau \right\}}{k_{\parallel}^{2} v_{A}^{2}}$$

 $\boldsymbol{\omega}_{\! 0}$ is given by the dispersion relation

$$1 + k_{y}^{2}\rho_{s}^{2}(1+\tau) - \frac{\omega_{*}}{\omega_{0}} - \frac{(\omega_{0} - \omega_{*})(\omega_{0} + \omega_{*}\tau)}{k_{\parallel}^{2}v_{A}^{2}} = 0$$

This dispersion relation has three roots, two Alfven waves with effects of diamagnetic drifts and one drift wave with finite beta effects



Dispersion Relation solved numerically

1. Solve for the "pump" mode eigenfrequency for finite beta drift wave and drift-Alfven wave

$$\Omega_0 [1 + k_y^2 \rho_s^2 (1 + \tau)] - 1 - \Omega_0 k_y^2 \rho_s^2 \hat{\beta} (\Omega_0 - 1) (\Omega_0 + \tau) = 0$$

where $\Omega_0 = \frac{\omega_0}{\omega_*}$ and $\hat{\beta} = \beta \frac{q^2 R^2}{2L_n^2}$

2. Use the eigenfrequency in dispersion relation for the shear flow/field to calculate growth rate

$$\hat{\gamma}_{z} = \left[\hat{M}_{A}(1-k_{y}^{2}\rho_{s}^{2}\Omega_{0}^{2}\hat{\beta}) + \hat{M}_{B}k_{x}^{2}\rho_{s}^{2}k_{y}^{2}\rho_{s}^{2}\Omega_{0}^{2}\hat{\beta} - \hat{\Delta}^{2}\right]^{1/2} \qquad \hat{\Delta}^{2} = \frac{1}{2}\left(\frac{\rho_{s}^{2}}{L_{n}^{2}}\right)\frac{(k_{x}^{2}\rho_{s}^{2})}{|\phi_{0}|^{2}}$$

Five dimensionless parameters :

(1)
$$k_x \rho_s$$
 (2) $k_y \rho_s$ (3) $\hat{\beta}$ (4) $|\phi_0| L_n / \rho_s$ (5) $\tau = \frac{T_i}{T_e}$



GROWTH RATE FOR ZONAL FLOW/FIELD $k_y \rho_s = 0.25, e\phi/T_e = \rho_s/L_n$

Dimensionless Parameters

(1)
$$k_y = k_y \rho_s$$
 (2) $k_x = k_x \rho_s$ (3) $\tau = T_i / T_e$ (4) $\Phi = \frac{e\phi}{T_e} \frac{L_n}{\rho_s}$ (5) $\overline{\beta} = (k_y \rho_s)^2 \hat{\beta}$

$$\hat{\beta} = \frac{\beta}{2} \frac{q^2 R^2}{L_n^2}$$
 Parameters: k_y ρ_s =0.25, τ =0, e ϕ_0 /T_e= ρ_s /L_n







GROWTH RATE FOR ZONAL FLOW/FIELD $k_y \rho_s = 0.25, e\phi/T_e = \rho_s/L_n$



THRESHOLD CONDITION FOR L-H TRANSITION MAXIMUM OF $(k_v \rho_s)^2 \hat{\beta}_c$ FOR $k_y \rho_s$, τ AND $e\phi/T_e$



GROWTH RATE FOR ZONAL FLOW/FIELD

Dispersion Relation for the growth of zonal flow/field $\begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}^2 \qquad \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$

$$\omega^{2} = \begin{bmatrix} \frac{1}{2} \frac{d^{2} \omega_{0}}{dk_{x}^{2}} k_{x}^{2} \\ \underbrace{\frac{1}{2} \frac{d^{2} \omega_{0}}{dk_{x}^{2}} k_{x}^{2}}_{Dispersion} \end{bmatrix} + \frac{\Gamma^{2}}{2 \omega_{0}} \frac{d^{2} \omega_{0}}{dk_{x}^{2}} k_{x}^{2} \begin{bmatrix} M_{A} \left(1 - \frac{\omega_{0}^{2}}{k_{\parallel}^{2} v_{A}^{2}} \right) + \underbrace{M_{B}}_{Zonal \ field} \frac{\omega_{0}^{2}}{k_{\parallel}^{2} v_{A}^{2}} \end{bmatrix} |\phi_{0}|^{2}$$
Reynold's Stress

Maxwell's Stress

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Generalized Lighthill Criterion for modulational instability

$$\frac{1}{\omega_0} \frac{d^2 \omega_0}{dk_x^2} \left[M_A \left(1 - \frac{\omega_0^2}{k_{\parallel}^2 v_A^2} \right) + M_B \frac{\omega_0^2}{k_{\parallel}^2 v_A^2} \right] < 0$$

Four finite β effects: (1) modification of dispersion

(2) modification of matrix element M_A (from side-band modes)

- (3) Maxwell Stress
- (4) Zonal field



GROWTH RATE FOR ZONAL FLOW/FIELD

Parameters: $k_y \rho_s$ =0.25, τ =0, $e \phi_0 / T_e = \rho_s / L_n$





For $\tau=1$, dominant drive is zonal-flow $\gamma_{zonal-flow}$



FIG. 4. Density perturbations: (a) electromagnetic, (b) electrostatic.



SCENARIO FOR L-H TRANSITION





 $(k_{y}\rho_{s})^{2}\hat{\beta}_{c}$ vs τ

k_yρ_s=0.025, 0.05, 0.1, 0.15, 0.2, 0.25, 0.3, 0.35, 0.4, 0.45, 0.5, 0.55, 0.6

 $(e\phi/T_e)^2 = (500.0, 200.0, 100.0, 50.0, 20.0, 10.0, 5.0, 2.0, 1.0, 0.5)(\rho_s/L_n)^2$





 $(k_{y}\rho_{s})^{2}\hat{\beta}_{c}$ vs τ

 $(e\phi/T_e)^2 = (500.0, 200.0, 100.0, 50.0, 20.0, 10.0, 5.0, 2.0, 1.0, 0.5)(\rho_s/L_n)^2$





CRITICAL PARAMETER Λ OR CRITICAL T_E

$$k_y^2 \rho_s^2 \hat{\beta} = 2.22/(1+1.9\tau^{0.8})$$

$$k_{y} = 2\pi/L_{0}, \quad L_{0} = 2\pi q \left(\frac{\nu_{ei}R\rho_{s}}{2\Omega_{e}}\right)^{1/2} \left(\frac{2R}{L_{n}}\right)^{1/2}$$

$$\frac{\rho_{\rm s}^2}{L_0^2} \left(\frac{4\pi nT_{\rm e}}{B^2}\right) \frac{q^2 R^2 (1+1.9\tau^{0.8})}{L_{\rm n}^2} = \frac{1.11}{2\pi^2}$$

$$T_{ec} (keV) = 0.46 \left(\frac{B^{2}(T)Z_{eff}}{1+1.9\tau^{0.8}}\right)^{1/3} \left(\frac{1}{R(m)A_{i}}\right)^{1/6} L_{n}^{1/2}(m)$$

$$OR$$

$$\Lambda = \frac{T_{e} (keV) (R(m)A_{i})^{1/6} (1+1.9\tau^{0.8})^{1/3}}{(B^{2}(T)Z_{eff})^{1/3} L_{n}^{1/2}(m)}, \text{ with } \Lambda_{c} = 0.46$$



DATA FROM DIII-D R. GROEBNER AND P. GOHIL

SHOT SERIES :078151, 078153, 078155, 078156

078161, 078165, 078167, 078169

084026, 084032, 084040, 084044

08830, 089348

102014, 102015, 102016, 102017 102025, 102026, 102029
$$\begin{split} &I_{p} \text{ scan (1.0-2.0 MA)} \\ &B_{T} = 2.1 \text{ T}, \text{ } n_{e} = 4.0 \text{ x} 10^{19} / \text{m}^{3} \\ &B_{T} \text{ scan (1.1-2.1 T)} \\ &I_{p} = 1.0 \text{ MA}, \text{ } n_{e} = 4.0 \text{ x} 10^{19} / \text{m}^{3} \\ &n_{e} \text{ scan (1.4 \text{ x} 10^{19} - 3.9 \text{ x} 10^{19} / \text{m}^{3})} \\ &I_{p} = 1.3 \text{ MA}, B_{T} = 2.1 \text{T} \end{split}$$

Random selection $B_T=2.1 \text{ T}$ $I_p=1.0 \text{ MA}$

different ∇B drift I_p=0.97 MA, B_T=2.1 T

SHOTS 96338, 96348

99559, 100162

Data T_e and L_n back-averaged over three points To remove fluctuations from "turbulence"



COMPARISON WITH DIII-D (IN COLLABORATION WITH R. GROEBNER)--2



$$\Lambda = \frac{T_{e}(\text{keV}) (R(m)A_{i})^{1/6}}{[B_{T}(T)]^{2/3} [L_{n}(m)]^{1/2} Z_{eff}^{1/3}}$$





COMPARISON WITH DIII-D





COMPARISON WITH DIII-D GRAD B TOWARDS AND AWAY FROM THE X POINT





COMPARISON WITH DIII-D GRAD B TOWARDS AND AWAY FROM X POINT

Shot #96338 (∇B drift to X point) — Shot #96348 (∇B drift away X point) —





GOHIL ET AL. PHY. REV LETT. 86, 644 (2001)



Strong reduction in L_n in the edge 2 msec prior to transition



COMPARISON WITH DIII-D WITH PELLET SHOTS 100162, 99559

Pellet Induced H mode





- Zonal flow responsible for saturation of finite β drift-wave turbulence
- Level of zonal flow determined by condition $V' = \gamma_{linear}$
- If zonal flow unstable for amplitudes BELOW stability criterion, turbulence not saturated => very large edge transport => leads to disruption (Greenwald limit)





•Derived generalized dispersion relation for shear/zonal flow with finite beta effects.

•Theory gives reasonable preliminary agreement with simulations and data on DIII-D and C-MOD

Future work

- undertake more careful study of the nonlocal dispersion relation
- study the low-dimensional nonlinear equations with finite beta to understand nature of the H mode attractor
 - -fixed point (non-ELMing),
 - -chaotic (ELMing)
- current theory is in terms of plasma parameters (T_e, T_i L_n) and not in terms of true control parameters. Use this simple expression in 1D and 2D predictive transport codes To obtain threshold power dependence and then make predictions for future devices
- Extend theory to core enhanced confinement modes



- Incorporate shaping effects in model for threshold for KH instability of zonal flows and finite beta drift wave/DRBM modes
- Explore the "interaction" region between the stability boundary for KH and LH to identify type of ELMS. ELMS are interplay between ballooning type modes and zonal and/or shear flow
- Extend study to full two dimensional eigenvalue stability of modes with shear to determine stability boundary more accurately
- Explore the connection of the "density-limit" boundary in $(\alpha_{\text{MHD}},\,\alpha_{\text{D}})$ space to the Greenwald limit



COMPARISONS

Scott NJP, 4, 52.1-52.30, (2002) Braginskii Equations

Scott IAEA-11-S7, (2005) Gyrokinetic Edge Code

