On Core-SOL Integration in Scenario Modelling for ITER

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Core-SOL integration: why?

- ISM goal: find a scenario providing necessary performance, consistent with available controls and satisfying technical limitations on all systems involved
- SOL/Divertor: one of such systems with limitations on target power loading, He removal and plasma detachment, controlling core fuelling and impurity contamination
- Over-simplified SOL models offer little help:
 - could provide separatrix *n* and *T*, but no neutrals, no geometry, no wall interactions
 - → no relation to technical limitations, no model of control actuators
 - such as gas puff, pumping speed or impurity injection
- No experiment yet in the parameter range of ITER
- → Internal consistence of the model extremely important



Core-SOL integration: how?

Scenario studies: long time scale (hundreds sec)

SOL/Divertor: time scale of tens msec \rightarrow quasi-steady-state

→ Direct coupling impractical:

SOL/Div much slower computationally

Indirect ("mediated") coupling:

parameterization of SOL/Div results

in terms of separatrix parameters

input: power and charged particle fluxes from core

(BC for SOL/Div)

output: n_i , T_e , T_i , Γ_n , E_n (BC for core)

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Produces solutions for the core consistent with SOL/Div

Translates SOL/Div constraints to the core

Avoids using non-controllable BC (e.g. n_{sep}) for the core

Being used now for operational window studies

Episode 7: integration with core

Different time scales for core and edge \rightarrow direct coupling impractical Scalings to parameterise SOLPS results \rightarrow b.c. for ASTRA (1D) ASTRA: pedestal model; (n, T, Γ_n , E_n) = F(q_⊥, Γ_i) at separatrix Control: P_{aux}, Γ_{core} for core; Γ_{puff} for q_{pk}, S_p for He \rightarrow real controls \rightarrow Operational window for the whole ITER consistent with divertor

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