

Linking Integrated Modelling to Tokamak Control Toolbox

Motivation: realistic modelling of a Tokamak experiment

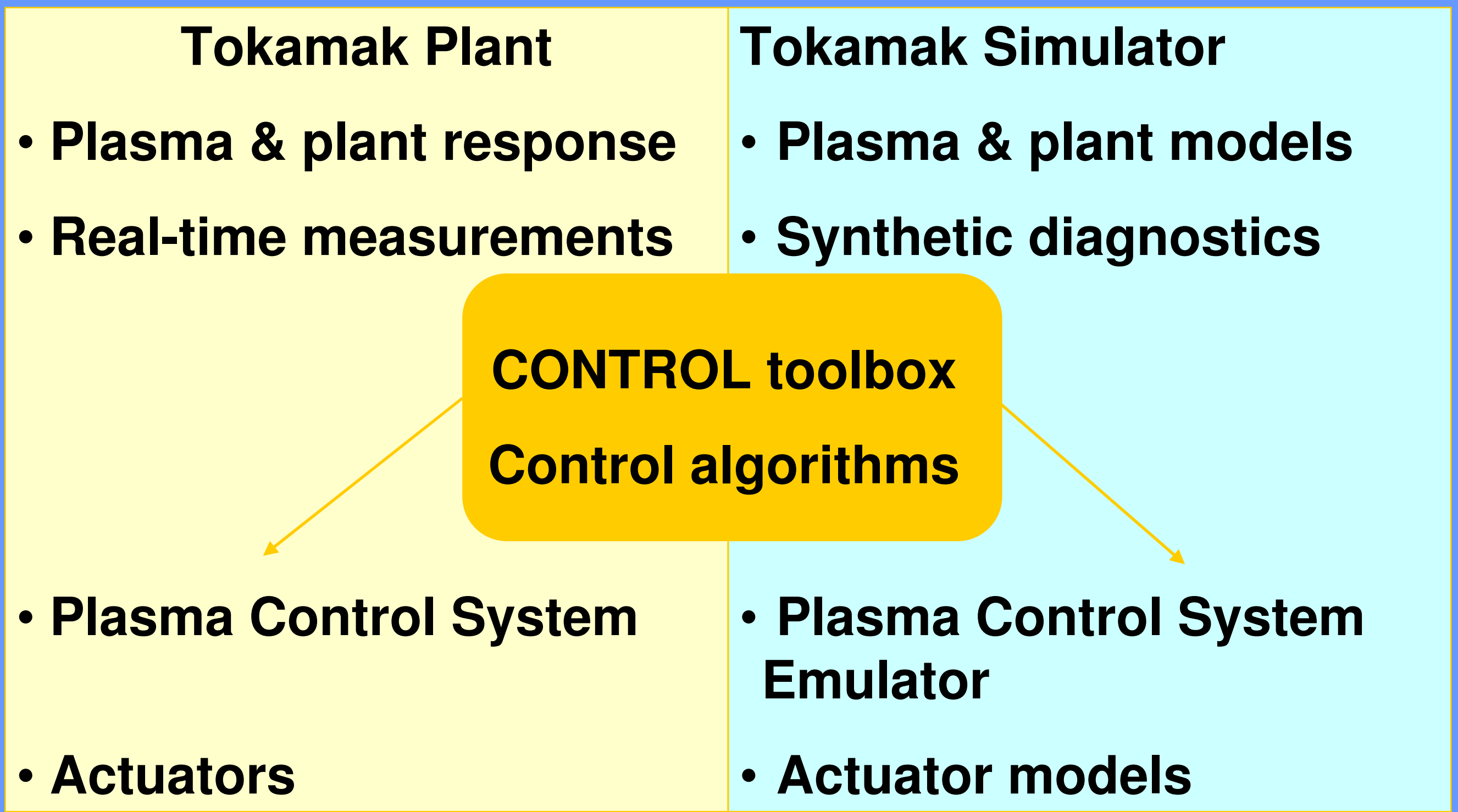
- Accurate plasma, actuators and sensors models
- Using the same control algorithms as the real experiment

Means

- Provide maximum Interoperability between the Integrated Modelling Framework and the tools used to design the Plasma Control System (PCS), typically: Simulink, Scicos

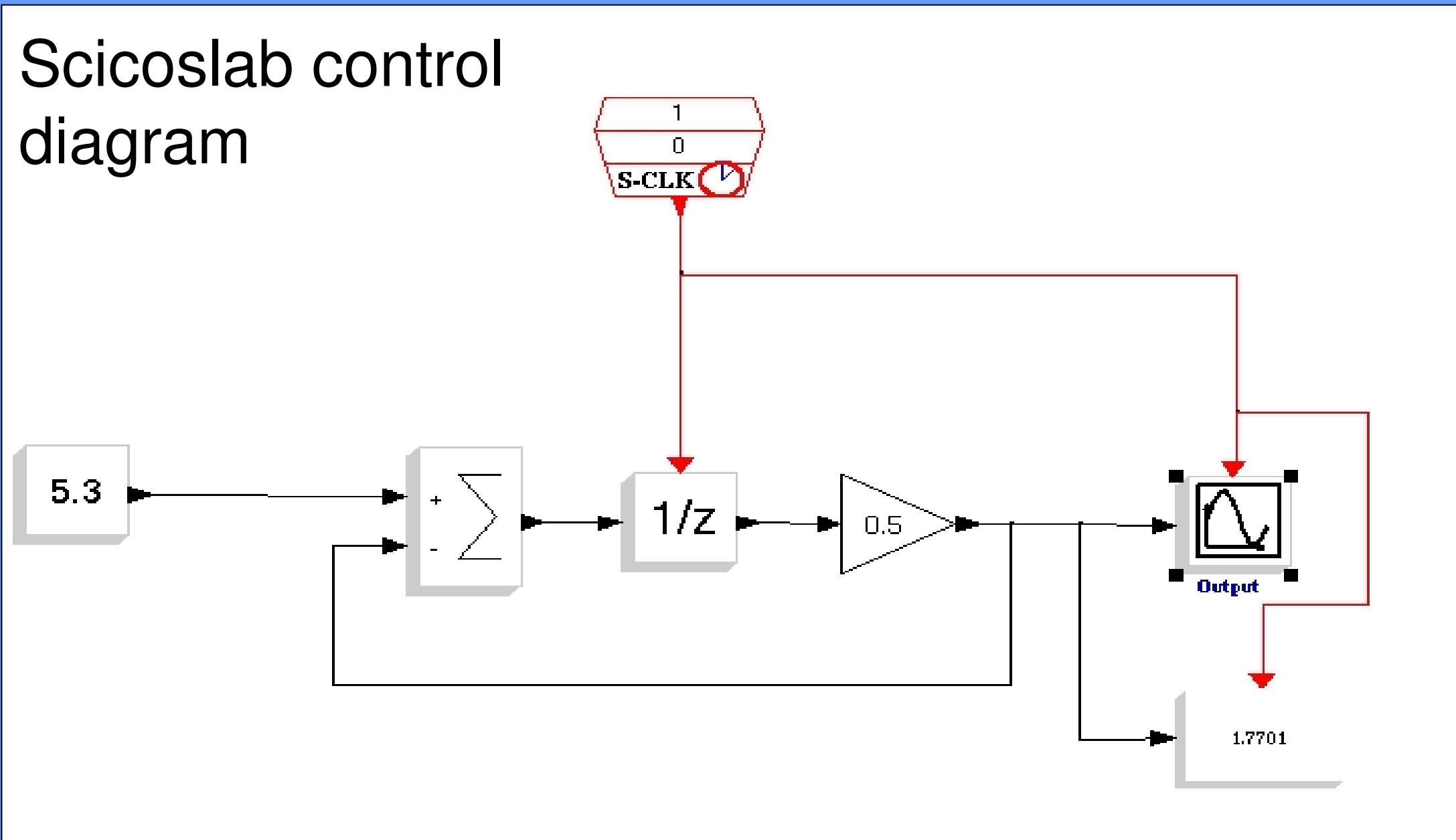
Applications

- Preparation of tokamak experiments by physicists
- Design and Test PCS algorithms with an accurate suite of plasma, actuators and sensors models
 - The PCS algorithms developed with the Modelling Framework can be plugged in directly into the real PCS of the experiment
- All these applications are geared towards ITER needs

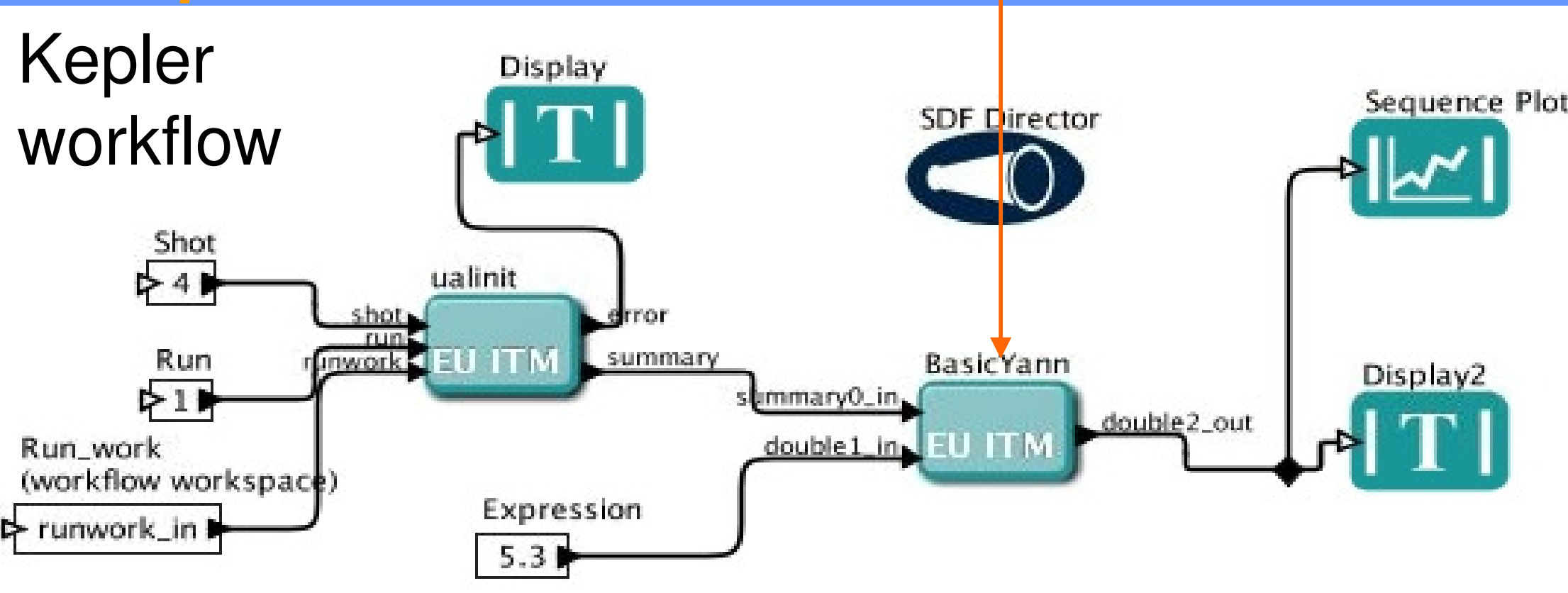


- ### ITM-TF Approach
- The Tokamak is simulated by the Integrated Modelling Framework
 - Handles Plasma, actuator and sensor models as usual
 - PCS emulator also included as a component of the Integrated Modelling workflow
 - Control algorithms are designed with standard tools of the Plasma Control community, i.e. Simulink or Scicos
 - The PCS Emulator is automatically generated from Simulink/Scicos and used as a component of the Integrated Modelling Framework
 - **This Approach has been implemented for both Simulink and Scicos under the ITM-TF framework**

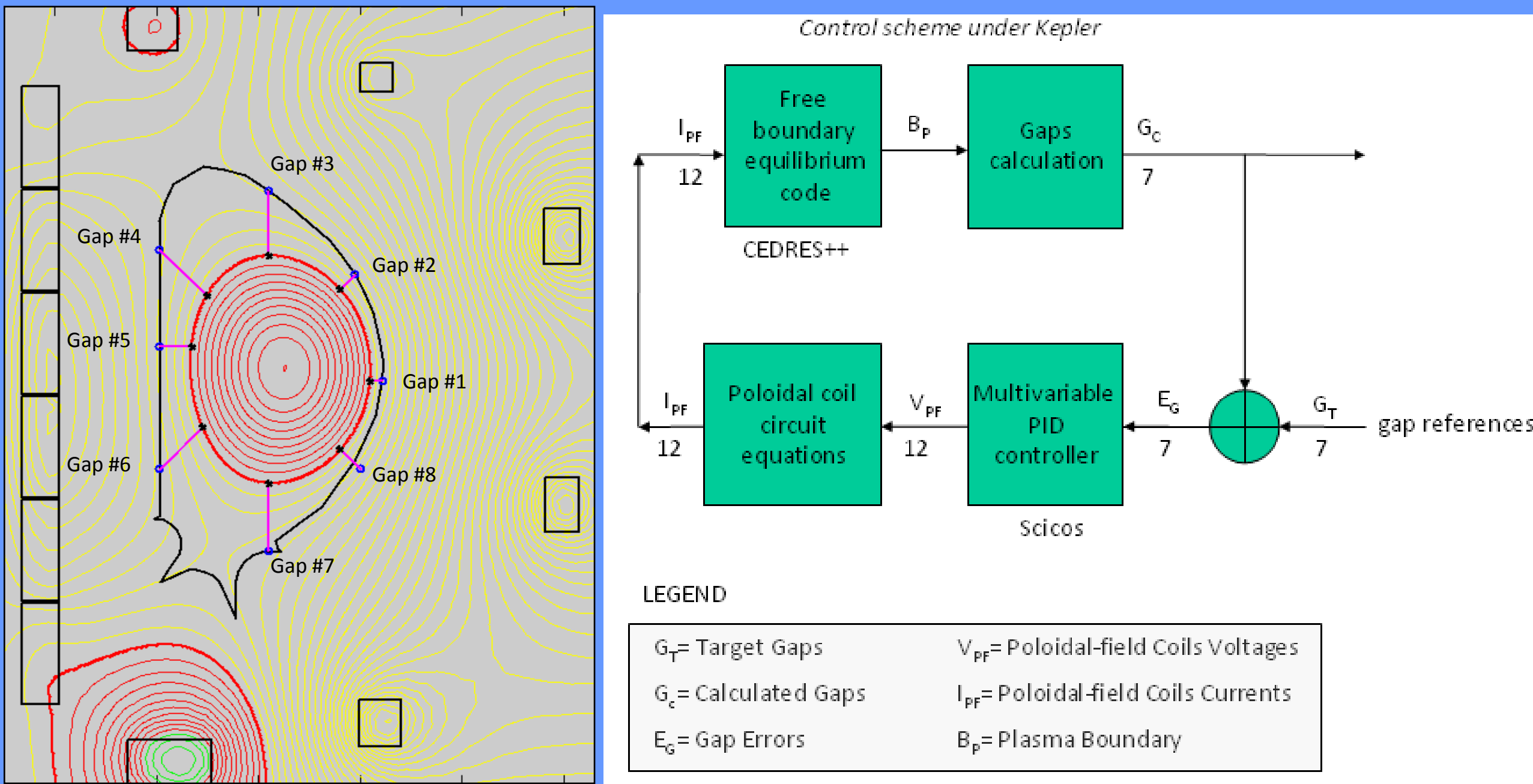
The ITM-TF Approach: Scicos or Simulink control diagrams are turned into a Kepler actor (or «component») and can then be used in the Integrated Modelling workflow



Automated generation of an IM workflow component

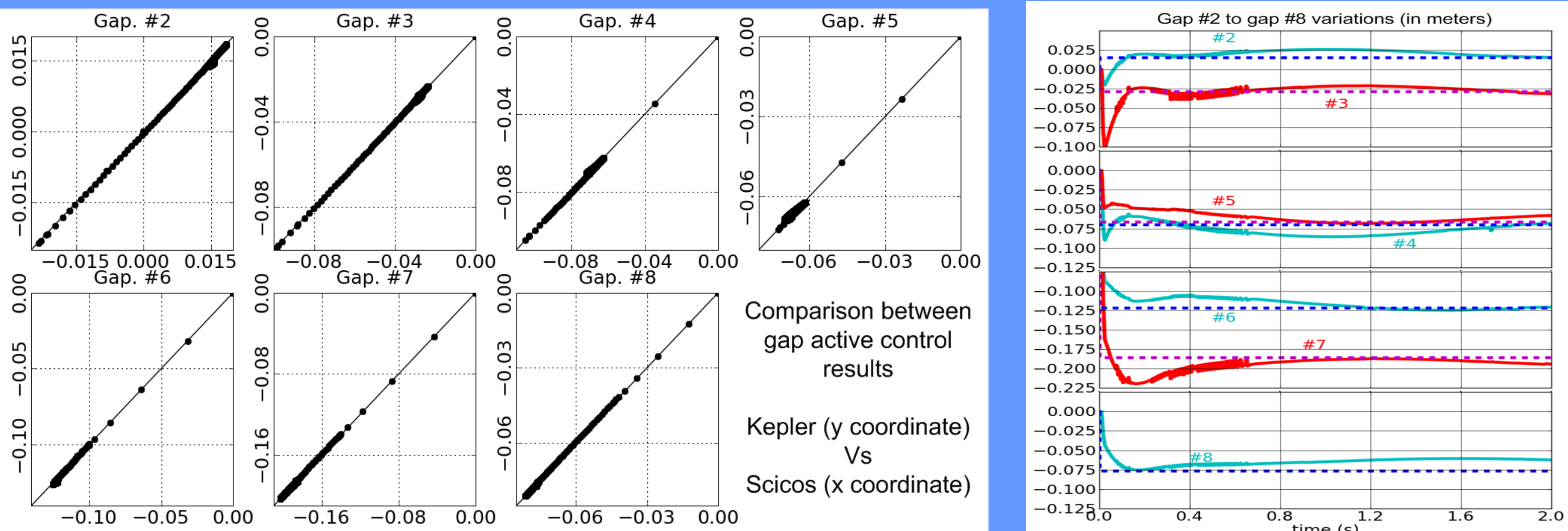


- ### Test case: ITER plasma shape control
- Control plasma shape via currents in the Poloidal Field (PF) coils
 - Free boundary equilibrium evolution and PF circuit equations
 - PID algorithm to control the PF voltages
 - Plasma shape characterized by « gaps »



Proof of Principle: for testing purposes, this simple tokamak simulator has been implemented in 3 ways

1. Fully under Scicos with linearized equilibrium model
2. Fully under Kepler, with controller generated from Scicos diagram (ITM-TF approach) and linearized equilibrium model
3. Fully under Kepler, with controller generated from Scicos diagram and direct use of CEDRES++ free boundary equilibrium code



Validation: implementations #1 and #2 yield the same results

Implementation #3 using the CEDRES++ model

Perspectives: more complex simulations, involving more sophisticated physics (e.g. full core transport + equilibrium + PF systems evolution) and controllers (fully realistic PCS algorithms, multiple controllers,...)

[O. Barana et al, FST 2011]